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**Determinant:** It can be used to solve the system of simultaneous equations

Consider the following three equations having three unknowns,  $x$ ,  $y$  and  $z$ .

$$a_1 x + b_1 y + c_1 z = 0$$

$$a_2 x + b_2 y + c_2 z = 0$$

$$a_3 x + b_3 y + c_3 z = 0$$

The determinant of these equations are as

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = 0$$

Which is determinant of third order

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix} - b_1 \begin{vmatrix} a_2 & c_2 \\ a_3 & c_3 \end{vmatrix} + c_1 \begin{vmatrix} a_2 & b_2 \\ a_3 & b_3 \end{vmatrix}$$

## MINOR

The minor of an element is defined as a determinant obtained by deleting the row and column containing the element.

Thus the minors of  $a_1$ ,  $b_1$  and  $c_1$  are respectively.

$$\begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix}, \begin{vmatrix} a_2 & c_2 \\ a_3 & c_3 \end{vmatrix} \text{ and } \begin{vmatrix} a_2 & b_2 \\ a_3 & b_3 \end{vmatrix}$$

$$\text{Thus } \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = a_1 (\text{minor of } a_1) - b_1 (\text{minor of } b_1) + c_1 (\text{minor of } c_1).$$

## COFACTORS

$$\text{Cofactor} = (-1)^{r+c} \text{ Minor}$$

where  $r$  is the number of rows of the element and  $c$  is the number of columns of the element.

The cofactor of any element of  $i$ th row and  $j$ th column is

$$(-1)^{i+j} \text{ minor}$$

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$$\text{Thus the cofactor of } a_1 = (-1)^{1+1} (b_2c_3 - b_3c_2) = + (b_2c_3 - b_3c_2)$$

$$\text{The cofactor of } b_1 = (-1)^{1+2} (a_2c_3 - a_3c_2) = - (a_2c_3 - a_3c_2)$$

$$\text{The cofactor of } c_1 = (-1)^{1+3} (a_2b_3 - a_3b_2) = + (a_2b_3 - a_3b_2)$$

$$\text{The determinant} = a_1 (\text{cofactor of } a_1) + a_2 (\text{cofactor of } a_2) + a_3 (\text{cofactor of } a_3).$$

**EX: Solve the determinant**

$$\begin{vmatrix} 3 & -1 & -2 \\ 0 & 0 & -1 \\ 3 & -5 & 0 \end{vmatrix}$$

**n.** We have, two zero entries in the second row. So, expanding along 2nd row:

$$\begin{vmatrix} 3 & -1 & -2 \\ 0 & 0 & -1 \\ 3 & -5 & 0 \end{vmatrix} = -0 \begin{vmatrix} -1 & -2 \\ -5 & 0 \end{vmatrix} + 0 \begin{vmatrix} 3 & -2 \\ 3 & 0 \end{vmatrix} - (-1) \begin{vmatrix} 3 & -1 \\ 3 & -5 \end{vmatrix} \\ = -0 + 0 + 1(-15 + 3) = -12$$

## PROPERTIES OF DETERMINANTS

**Property (i).** *The value of a determinant remains unaltered; if the rows are interchanged into columns (or the columns into rows).*

**(ii).** *If two rows (or two columns) of a determinant are interchanged, the sign of the value of the determinant changes.*

**(iii).** *If two rows (or columns) of a determinant are identical, the value of the determinant is zero.*

**(iv).** *If the elements of any row (or column) of a determinant be each multiplied by the same number, the determinant is multiplied by that number.*

**(v).** *The value of the determinant remains unaltered if to the elements of one row (or column) be added any constant multiple of the corresponding elements of any other row (or column) respectively.*

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EX

By using property of determinants prove that

$$\begin{vmatrix} 1 & x & x^2 \\ x^2 & 1 & x \\ x & x^2 & 1 \end{vmatrix} = (1-x^3)^2$$

EX

Without expanding the determinant, prove that

$$\begin{vmatrix} 1 & a & b+c \\ 1 & b & c+a \\ 1 & c & a+b \end{vmatrix} = 0.$$

EX

Prove that

$$\begin{vmatrix} -a^2 & ab & ac \\ ba & -b^2 & bc \\ ac & bc & -c^2 \end{vmatrix} = 4a^2b^2c^2$$

EX

Expand the following determinants, using properties of the determinants :

1.  $\begin{vmatrix} 1 & 3 & 7 \\ 4 & 9 & 1 \\ 2 & 7 & 6 \end{vmatrix}$

Ans. 51.

2.  $\begin{vmatrix} x & a & a \\ a & x & a \\ a & a & x \end{vmatrix}$

Ans.  $(x+2a)(x-a)^2$

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## SPECIAL TYPE OF DETERMINANT

(i) **Ortho-symmetric Determinant.** If every element of the leading diagonal is the same and the equidistant elements from the diagonal are equal, then the determinant is said to be ortho-symmetric determinant.

$$\begin{vmatrix} a & h & g \\ h & a & f \\ g & f & a \end{vmatrix}$$

(ii) **Skew-Symmetric Determinant.** If the elements of the leading diagonal are all zero and every other element is equal to its conjugate with sign changed, the determinant is said to be Skew-symmetric.

$$\begin{vmatrix} 0 & -a & -b \\ a & 0 & -c \\ b & c & 0 \end{vmatrix}$$

**Property 1.** A Skew-symmetric determinant of odd order vanishes.

## APPLICATION OF DETERMINANTS

**Area of triangle.** We know that the area of a triangle, whose vertices are  $(x_1, y_1)$ ,  $(x_2, y_2)$  and  $(x_3, y_3)$  is given by

$$\Delta = \frac{1}{2} [x_1(y_2 - y_3) - x_2(y_1 - y_3) + x_3(y_1 - y_2)]$$

**Note.** Since area is always a positive quantity, therefore we always take the absolute value of the determinant for the area.

**Condition of collinearity of three points.** Let  $A(x_1, y_1)$ ,  $B(x_2, y_2)$  and  $C(x_3, y_3)$  be three points. Then,  $A, B, C$  are collinear

$$\Leftrightarrow \text{area of triangle } ABC = 0$$

## SOLUTION OF SIMULTANEOUS LINEAR EQUATIONS BY DETERMINANTS (CRAMER'S RULE)

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## PRODUCT OF DETERMINANT

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} \times \begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix}$$

Product of the given determinants

$$= \begin{vmatrix} a_1\alpha_1 + b_1\beta_1 + c_1\gamma_1 & a_1\alpha_2 + b_1\beta_2 + c_1\gamma_2 & a_1\alpha_3 + b_1\beta_3 + c_1\gamma_3 \\ a_2\alpha_1 + b_2\beta_1 + c_2\gamma_1 & a_2\alpha_2 + b_2\beta_2 + c_2\gamma_2 & a_2\alpha_3 + b_2\beta_3 + c_2\gamma_3 \\ a_3\alpha_1 + b_3\beta_1 + c_3\gamma_1 & a_3\alpha_2 + b_3\beta_2 + c_3\gamma_2 & a_3\alpha_3 + b_3\beta_3 + c_3\gamma_3 \end{vmatrix}$$

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## MATRICES

The system of numbers arranged in a rectangular array in a rows & columns and bounded by bracket is called matrices

It has got 3 rows and 4 columns and in all  $3 \times 4 = 12$  elements. It is termed as  $3 \times 4$  matrix, to be read as [3 by 4 matrix]. In the double subscripts of an element, the first subscript determines the row and the second subscript determines the column in which the element lies,  $a_{ij}$  lies in the  $i$ th row and  $j$ th column.

$$A = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 4 & 2 & 5 & 7 \\ 3 & 4 & 2 & 6 \end{bmatrix}$$



## VARIOUS TYPES OF MATRICES

(i) **Row Matrix.** If a matrix has only one row and any number of columns, it is called a *Row matrix*, e.g.,

$$[2 \ 7 \ 3 \ 9]$$

(b) **Column Matrix.** A matrix, having one column and any number of rows, is called a *Column matrix*, e.g.,

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

(c) **Null Matrix or Zero Matrix.** Any matrix, in which all the elements are zeros, is called a *Zero matrix or Null matrix* e.g.,

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

(d) **Square Matrix.** A matrix, in which the number of rows is equal to the number of columns, is called a square matrix e.g.,

$$\begin{bmatrix} 2 & 5 \\ 1 & 4 \end{bmatrix}$$

(e) **Diagonal Matrix.** A square matrix is called a diagonal matrix, if all its non-diagonal elements are zero e.g.,

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

(f) **Scalar matrix.** A diagonal matrix in which all the diagonal elements are equal to a scalar, say ( $k$ ) is called a scalar matrix.

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- (g) **Unit or Identity Matrix.** A square matrix is called a unit matrix if all the diagonal elements are unity and non-diagonal elements are zero *e.g.*,

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

- (h) **Symmetric Matrix.** A square matrix will be called symmetric, if for all values of  $i$  and  $j$ ,  $a_{ij} = a_{ji}$  *i.e.*,  $A' = A$

*e.g.*, 
$$\begin{bmatrix} a & h & g \\ h & b & f \\ g & f & c \end{bmatrix}$$

- (i) **Skew Symmetric Matrix.** A square matrix is called skew symmetric matrix, if  
(1)  $a_{ij} = -a_{ji}$  for all values of  $i$  and  $j$ , or  $A' = -A$   
(2) All diagonal elements are zero, *e.g.*,

$$\begin{bmatrix} 0 & -h & -g \\ h & 0 & -f \\ g & f & 0 \end{bmatrix}$$

- (j) **Triangular Matrix.** (Echelon form) A square matrix, all of whose elements below the leading diagonal are zero, is called an *upper triangular matrix*. A square matrix, all of whose elements above the leading diagonal are zero, is called a *lower triangular matrix* *e.g.*,

$$\begin{bmatrix} 1 & 3 & 2 \\ 0 & 4 & 1 \\ 0 & 0 & 6 \end{bmatrix}$$

Upper triangular matrix

$$\begin{bmatrix} 2 & 0 & 0 \\ 4 & 1 & 0 \\ 5 & 6 & 7 \end{bmatrix}$$

Lower triangular matrix

- (k) **Transpose of a Matrix.** If in a given matrix  $A$ , we interchange the rows and the corresponding columns, the new matrix obtained is called the transpose of the matrix  $A$  and is denoted by  $A'$  or  $A^T$  *e.g.*,

$$A = \begin{bmatrix} 2 & 3 & 4 \\ 1 & 0 & 5 \\ 6 & 7 & 8 \end{bmatrix}, A' = \begin{bmatrix} 2 & 1 & 6 \\ 3 & 0 & 7 \\ 4 & 5 & 8 \end{bmatrix}$$

- (l) **Orthogonal Matrix.** A square matrix  $A$  is called an orthogonal matrix if the product of the matrix  $A$  and the transpose matrix  $A'$  is an identity matrix *e.g.*,

$$A \cdot A' = I$$

if  $|A| = 1$ , matrix  $A$  is proper.

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**(m) Conjugate of a Matrix**

Let 
$$A = \begin{bmatrix} 1+i & 2-3i & 4 \\ 7+2i & -i & 3-2i \end{bmatrix}$$

Conjugate of matrix  $A$  is  $\bar{A}$

$$\bar{A} = \begin{bmatrix} 1-i & 2+3i & 4 \\ 7-2i & i & 3+2i \end{bmatrix}$$

**(n) Matrix  $A^\theta$ .** Transpose of the conjugate of a matrix  $A$  is denoted by  $A^\theta$ .

Let 
$$A = \begin{bmatrix} 1+i & 2-3i & 4 \\ 7+2i & -i & 3-2i \end{bmatrix}$$

$$\bar{A} = \begin{bmatrix} 1-i & 2+3i & 4 \\ 7-2i & +i & 3+2i \end{bmatrix}$$

$$(\bar{A})' = \begin{bmatrix} 1-i & 7-2i \\ 2+3i & i \\ 4 & 3+2i \end{bmatrix}$$

$$A^\theta = \begin{bmatrix} 1-i & 7-2i \\ 2+3i & i \\ 4 & 3+2i \end{bmatrix}$$

**(o) Unitary Matrix.** A square matrix  $A$  is said to be unitary if

$$A^\theta A = I$$

$$A = \begin{bmatrix} \frac{1+i}{2} & \frac{-1+i}{2} \\ \frac{1+i}{2} & \frac{1-i}{2} \end{bmatrix}, \quad A^\theta = \begin{bmatrix} \frac{1-i}{2} & \frac{1-i}{2} \\ \frac{-1-i}{2} & \frac{1+i}{2} \end{bmatrix}, \quad A \cdot A^\theta = I$$

**(p) Hermitian Matrix.** A square matrix  $A = (a_{ij})$  is called Hermitian matrix, if every  $i$ - $j$ th element of  $A$  is equal to conjugate complex  $j$ - $i$ th element of  $A$ .

In other words,  $a_{ij} = \bar{a}_{ji}$

$$\begin{bmatrix} 1 & 2+3i & 3+i \\ 2-3i & 2 & 1-2i \\ 3-i & 1+2i & 5 \end{bmatrix}$$

Necessary and sufficient condition for a matrix  $A$  to be Hermitian is that  $A = A^\theta$  i.e. conjugate transpose of  $A$

$$\Rightarrow A = (\bar{A})'$$

**(q) Skew Hermitian Matrix.** A square matrix  $A = (a_{ij})$  will be called a Skew Hermitian matrix if every  $i$ - $j$ th element of  $A$  is equal to negative conjugate complex of  $j$ - $i$ th element of  $A$ .

In other words,  $a_{ij} = -\bar{a}_{ji}$

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(r) **Idempotent Matrix.** A matrix, such that  $A^2 = A$  is called Idempotent Matrix.

(s) **Periodic Matrix.** A matrix  $A$  will be called a Periodic Matrix, if

$$A^{k+1} = A$$

where  $k$  is a +ve integer. If  $k$  is the least +ve integer, for which  $A^{k+1} = A$ , then  $k$  is said to be the period of  $A$ . If we choose  $k = 1$ , we get  $A^2 = A$  and we call it to be idempotent matrix.

(t) **Nilpotent Matrix.** A matrix will be called a Nilpotent matrix, if  $A^k = 0$  (null matrix) where  $k$  is a +ve integer ; if however  $k$  is the least +ve integer for which  $A^k = 0$ , then  $k$  is the *index* of the nilpotent matrix.

$$\text{e.g., } A = \begin{bmatrix} ab & b^2 \\ -a^2 & -ab \end{bmatrix}, A^2 = \begin{bmatrix} ab & b^2 \\ -a^2 & -ab \end{bmatrix} \begin{bmatrix} ab & b^2 \\ -a^2 & -ab \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0$$

$A$  is nilpotent matrix whose index is 2.

(u) **Involuntary Matrix.** A matrix  $A$  will be called an Involuntary matrix, if  $A^2 = I$  (unit matrix). Since  $I^2 = I$  always  $\therefore$  Unit matrix is involuntary.

(v) **Equal Matrices.** Two matrices are said to be equal if

(i) They are of the same order.

(ii) The elements in the corresponding positions are equal.

Thus if 
$$A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}, B = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$$

Here 
$$A = B$$

(w) **Singular Matrix.** If the determinant of the matrix is zero, then the matrix is known as

singular matrix e.g.  $A = \begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$  is singular matrix, because  $|A| = 6 - 6 = 0$ .

NOTE

Square matrix = Symmetric matrix + Anti-symmetric matrix

## PROPERTIES OF MATRIX ADDITION

Only matrices of the same order can be added or subtracted.

(i) **Commutative Law.**  $A + B = B + A$ .

(ii) **Associative law.**  $A + (B + C) = (A + B) + C$ .



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## SUBTRACTION OF MATRICES

The difference of two matrices is a matrix, each element of which is obtained by subtracting the elements of the second matrix from the corresponding element of the first.

$$A - B = [a_{ij} - b_{ij}]$$

## MULTIPLICATION

The product of two matrices  $A$  and  $B$  is only possible if the number of columns in  $A$  is equal to the number of rows in  $B$ .

NOTE

$$(AB)' = B'A'$$

If  $A$  and  $B$  are two matrices conformal for product  $AB$ , then show that  $(AB)' = B'A'$ , where dash represents transpose of a matrix.

## PROPERTIES OF MATRIX MULTIPLICATION

1. Multiplication of matrices is not commutative.

$$AB \neq BA$$

2. Matrix multiplication is associative, if conformability is assured.

$$A(BC) = (AB)C$$

3. Matrix multiplication is distributive with respect to addition.

$$A(B + C) = AB + AC$$

4. Multiplication of matrix  $A$  by unit matrix.

$$AI = IA = A$$

5. Multiplicative inverse of a matrix exists if  $|A| \neq 0$ .

$$A \cdot A^{-1} = A^{-1} \cdot A = I$$

6. If  $A$  is a square then  $A \times A = A^2$ ,  $A \times A \times A = A^3$ .

7.  $A^0 = I$

8.  $I^n = I$ , where  $n$  is positive integer.

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ADJOINT OF MATRIX: The transpose of the matrix of Cofactor

## PROPERTY OF ADJOINT MATRIX

The product of a matrix  $A$  and its adjoint is equal to unit matrix multiplied by the determinant  $A$ .

If  $A$  be a square matrix, then  $(\text{Adjoint } A) \cdot A = A \cdot (\text{Adjoint } A) = |A| \cdot I$

## INVERSE OF MATRIX

If  $A$  and  $B$  are two square matrices of the same order, such that

$$AB = BA = I$$

( $I$  = unit matrix)

then  $B$  is called the inverse of  $A$  i.e.  $B = A^{-1}$  and  $A$  is the inverse of  $B$ .

Condition for a square matrix  $A$  to possess an inverse is that matrix  $A$  is non-singular, i.e.,  $|A| \neq 0$

If  $A$  is a square matrix and  $B$  be its inverse, then  $AB = I$

Taking determinant of both sides, we get

$$|AB| = |I| \text{ or } |A| |B| = |I|$$

From this relation it is clear that  $|A| \neq 0$

i.e. the matrix  $A$  is non-singular.

$$A^{-1} = \frac{1}{|A|} (\text{Adj. } A)$$

NOTE

If  $A$  and  $B$  are non-singular matrices of the same order then,

$$(AB)^{-1} = B^{-1} \cdot A^{-1}$$

$(A^{-1})^m = (A^m)^{-1}$  for any positive integer  $m$

## RANK OF A MATRIX

The rank of a matrix is said to be  $r$  if

- (a) It has at least one non-zero minor of order  $r$ .
- (b) Every minor of  $A$  of order higher than  $r$  is zero.

**Note:** (i) Non-zero row is that row in which all the elements are not zero.

(ii) The rank of the product matrix  $AB$  of two matrices  $A$  and  $B$  is less than the rank of either of the matrices  $A$  and  $B$ .

(iii) Corresponding to every matrix  $A$  of rank  $r$ , there exist non-singular matrices  $P$  and  $Q$  such

that  $PAQ = \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}$

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## RANK OF MATRIX BY TRIANGULAR FORM

**Rank = Number of non-zero row in upper triangular matrix.**

**Note.** Non-zero row is that row which does not contain all the elements as zero.

## TYPES OF LINEAR EQUATIONS

(1) **Consistent.** A system of equations is said to be *consistent*, if they have one or more solution *i.e.*

$$x + 2y = 4$$

$$3x + 2y = 2$$

Unique solution

$$x + 2y = 4$$

$$3x + 6y = 12$$

Infinite solution

(2) **Inconsistent.** If a system of equation has no solution, it is said to be *inconsistent i.e.*

$$x + 2y = 4$$

$$3x + 6y = 5$$

LET

$$C = [A, B]$$

is called the **augmented matrix**.

$$[A:B] = C$$

(a) **Consistent equations.** If  $\text{Rank } A = \text{Rank } C$

(i) *Unique solution:*  $\text{Rank } A = \text{Rank } C = n$

(ii) *Infinite solution:*  $\text{Rank } A = \text{Rank } C = r, r < n$

(b) **Inconsistent equations.** If  $\text{Rank } A \neq \text{Rank } C$ .

## LINEARLY DEPENDENCE AND INDEPENDENCE OF VECTORS BY RANK METHOD

1. If the rank of the matrix of the given vectors is equal to number of vectors, then the vectors are linearly independent.
2. If the rank of the matrix of the given vectors is less than the number of vectors, then the vectors are linearly dependent.

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## PARTITIONING OF MATRICES

**Sub matrix.** A matrix obtained by deleting some of the rows and columns of a matrix  $A$  is said to be sub matrix.

For example,  $A = \begin{bmatrix} 4 & 1 & 0 \\ 5 & 2 & 1 \\ 6 & 3 & 4 \end{bmatrix}$ , then  $\begin{bmatrix} 4 & 1 \\ 5 & 2 \end{bmatrix}$ ,  $\begin{bmatrix} 5 & 2 \\ 6 & 3 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$  are the sub matrices.

**Partitioning:** A matrix may be subdivided into sub matrices by drawing lines parallel to its rows and columns. These sub matrices may be considered as the elements of the original matrix.

## EIGEN VALUE & EIGEN VECTOR

Let  $X$  be a such vector which transforms into  $\lambda X$  by means of the transformation (1). Suppose the linear transformation  $Y = AX$  transforms  $X$  into a scalar multiple of itself i.e.  $\lambda X$ .

$$\begin{aligned} AX &= Y = \lambda X \\ AX - \lambda IX &= 0 \\ (A - \lambda I)X &= 0 \end{aligned}$$

Thus the unknown scalar  $\lambda$  is known as an eigen value of the matrix  $A$  and the corresponding non zero vector  $X$  as **eigen vector**.

**Characteristic Polynomial:** The determinant  $|A - \lambda I|$  when expanded will give a polynomial, which we call as characteristic polynomial of matrix  $A$ .

**Characteristic Equation:** The equation  $|A - \lambda I| = 0$  is called the characteristic equation of the matrix  $A$  e.g.

**Characteristic Roots or Eigen Values:** The roots of characteristic equation  $|A - \lambda I| = 0$  are called characteristic roots of matrix  $A$ . e.g.

## PROPERTIES OF EIGEN VALUES

(1) Any square matrix  $A$  and its transpose  $A'$  have the same eigen values.

**Note.** The sum of the elements on the principal diagonal of a matrix is called the **trace** of the matrix.

(2) The sum of the eigen values of a matrix is equal to the **trace** of the matrix.

(3) The product of the eigen values of a matrix  $A$  is equal to the **determinant** of  $A$ .

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(4) If  $\lambda_1, \lambda_2, \dots, \lambda_n$  are the eigen values of  $A$ , then the eigen values of

(i)  $kA$  are  $k\lambda_1, k\lambda_2, \dots, k\lambda_n$  (ii)  $A^m$  are  $\lambda_1^m, \lambda_2^m, \dots, \lambda_n^m$

(iii)  $A^{-1}$  are  $\frac{1}{\lambda_1}, \frac{1}{\lambda_2}, \dots, \frac{1}{\lambda_n}$ .

## POWER OF MATRIX (by Cayley Hamilton Theorem)

Any positive integral power  $A^m$  of matrix  $A$  is linearly expressible in terms of those of lower degree, where  $m$  is a positive integer and  $n$  is the degree of characteristic equation such that  $m > n$ .

## PROPERTIES OF EIGEN VECTORS

1. The eigen vector  $X$  of a matrix  $A$  is not unique.
2. If  $\lambda_1, \lambda_2, \dots, \lambda_n$  be distinct eigen values of an  $n \times n$  matrix then corresponding eigen vectors  $X_1, X_2, \dots, X_n$  form a linearly independent set.
3. If two or more eigen values are equal it may or may not be possible to get linearly independent eigen vectors corresponding to the equal roots.
4. Two eigen vectors  $X_1$  and  $X_2$  are called orthogonal vectors if  $X_1' X_2 = 0$ .
5. Eigen vectors of a symmetric matrix corresponding to different eigen values are orthogonal.

**Normalised form of vectors.** To find normalised form of  $\begin{bmatrix} a \\ b \\ c \end{bmatrix}$ , we divide each element by

$$\sqrt{a^2 + b^2 + c^2}.$$

For example, normalised form of  $\begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$  is  $\begin{bmatrix} 1/3 \\ 2/3 \\ 2/3 \end{bmatrix}$

$$\left[ \sqrt{1^2 + 2^2 + 2^2} = 3 \right]$$

EX

If  $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ , find  $A^{100}$ .

$$= \begin{bmatrix} 2^{100} & 0 \\ 0 & 1 \end{bmatrix}$$

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## SYLVESTER THEOREM

Let  $P(A) = C_0 A^n + C_1 A^{n-1} + C_2 A^{n-2} + \dots + C_{n-1} A + C_n I$

and  $|\lambda I - A| = f(\lambda)$  and Adjoint matrix of  $[\lambda I - A] = [f(\lambda)]$

$$z(\lambda) = \frac{[f(\lambda)]}{f'(\lambda)} = \frac{\text{Adjoint matrix of } [\lambda I - A]}{f'(\lambda)}$$

Then according to Sylvester's theorem

$$P(A) = P(\lambda_1). Z(\lambda_1) + P(\lambda_2). Z(\lambda_2) + P(\lambda_3). Z(\lambda_3) + \dots$$

$$= \sum_{r=1}^n P(\lambda_r). Z(\lambda_r)$$

This theorem is used to find out the power of Matrix

## COMPLEX MATRICES

**Conjugate of a matrix.** The matrix formed by replacing the elements of a matrix by their respective conjugate numbers is called the conjugate of  $A$  and is denoted by  $\bar{A}$ .

$$A = (a_{ij})_{m \times n}, \text{ then } \bar{A} = (\bar{a}_{ij})_{m \times n}$$

Example

$$\text{If } A = \begin{bmatrix} 3+4i & 2-i & 4 \\ i & 2 & -3i \end{bmatrix} \text{ then } \bar{A} = \begin{bmatrix} 3-4i & 2+i & 4 \\ -i & 2 & 3i \end{bmatrix}$$